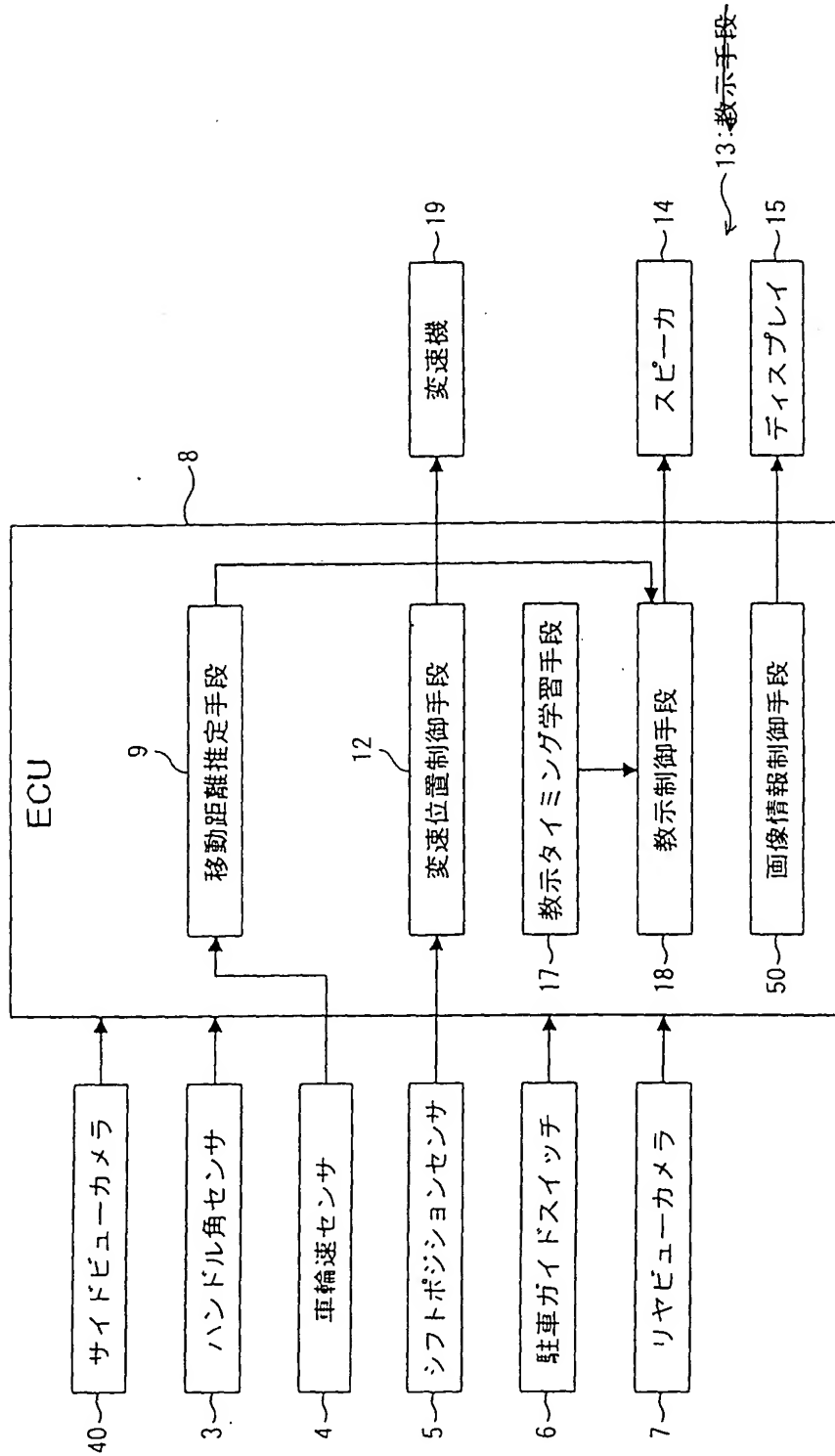


FIG. 1



[図 2]

FIG. 2

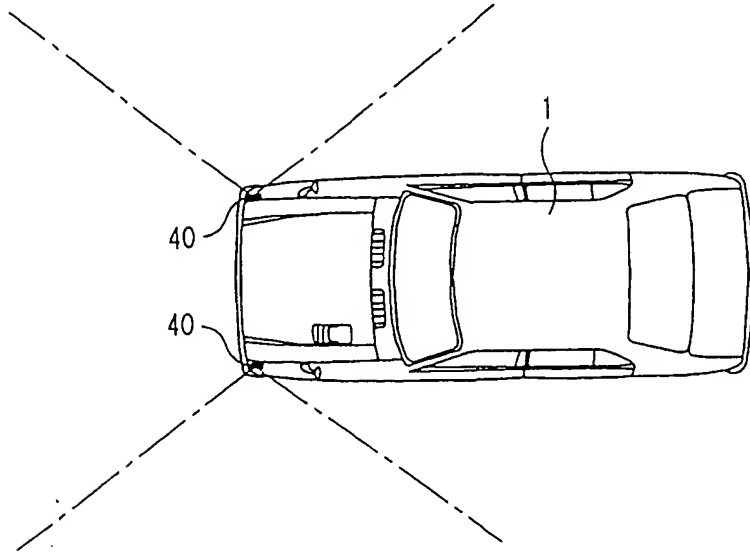


FIG. 3A

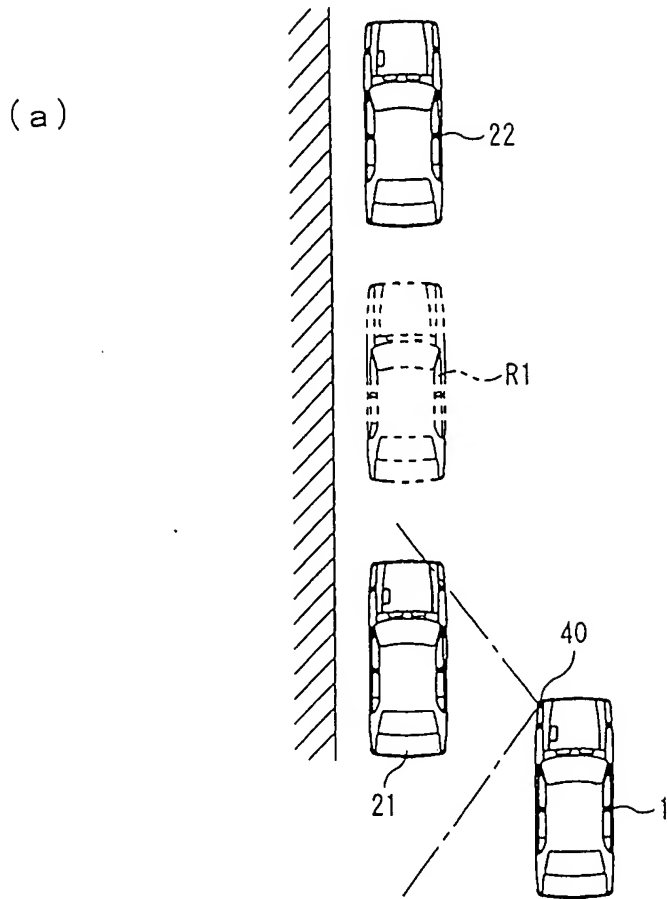


FIG. 3B

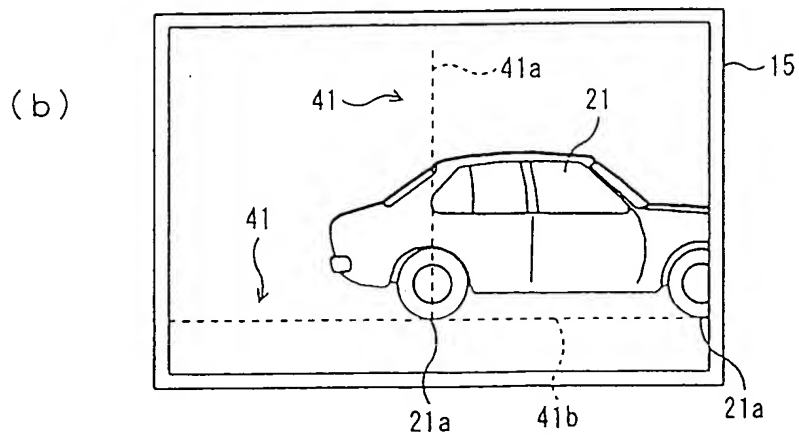


FIG. 4A
(a)

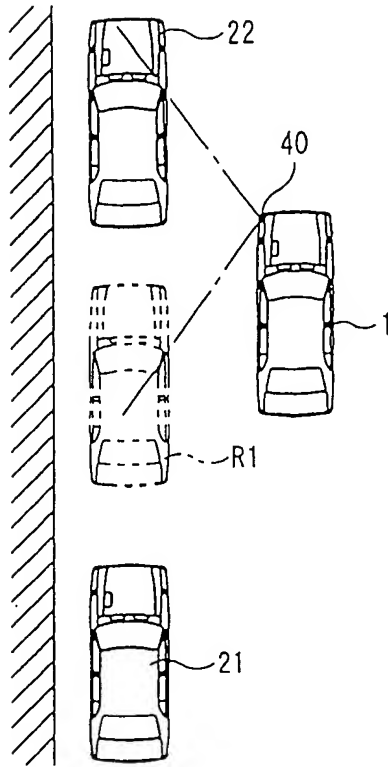


FIG. 4B

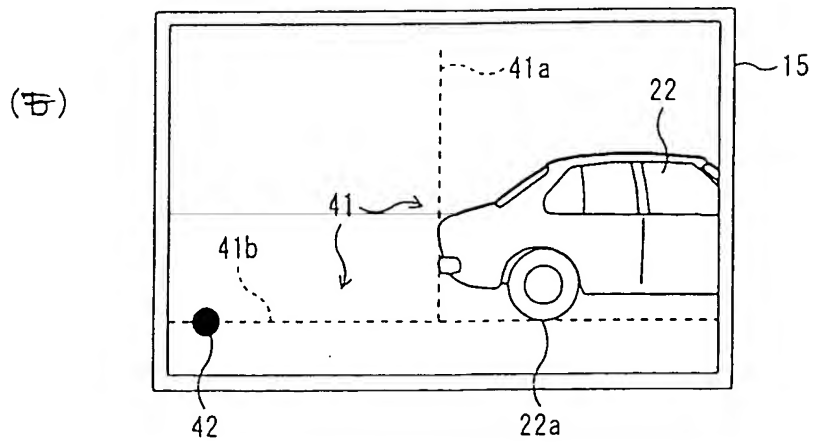


FIG. 4C

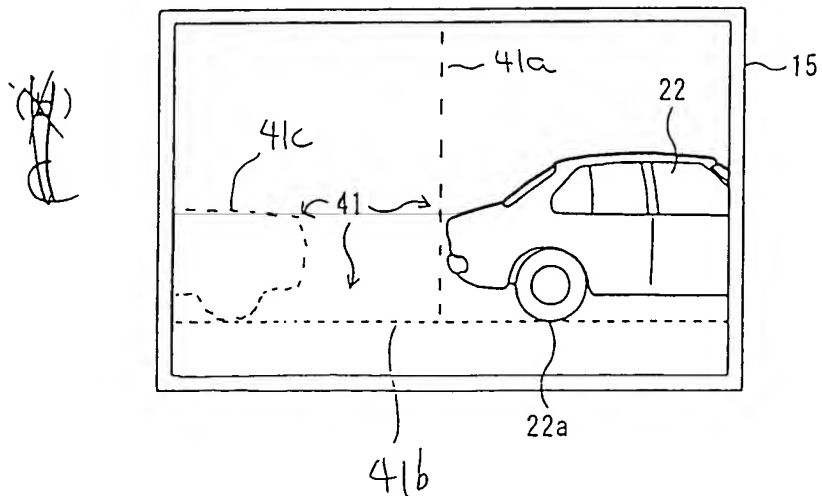


FIG. 5A

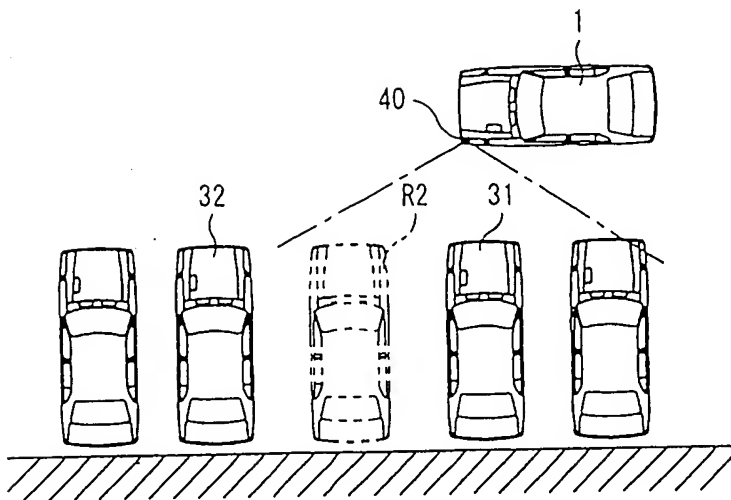


FIG. 5B

(b)

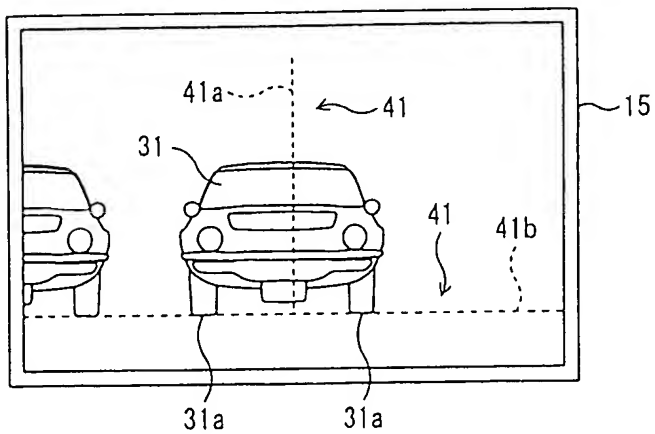


FIG. 6A

(a)

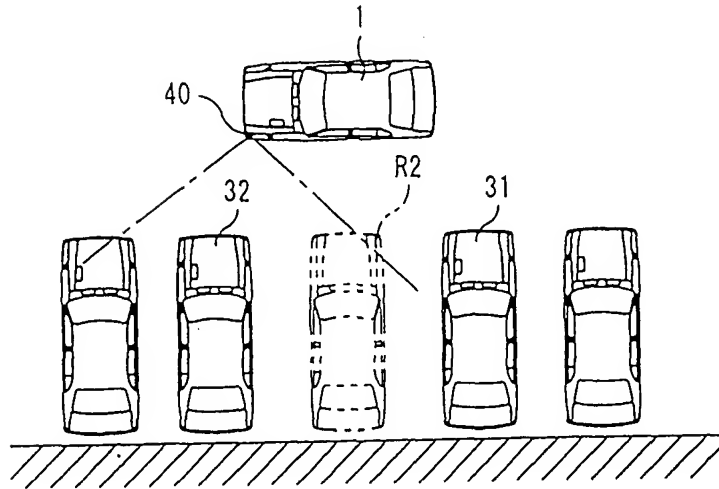


FIG. 6B

(b)

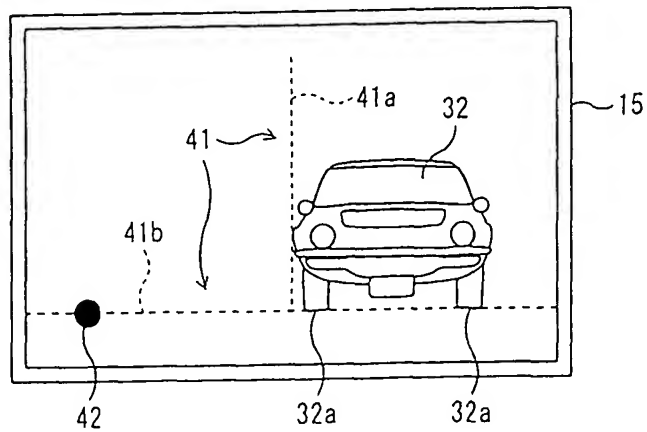


FIG. 6C

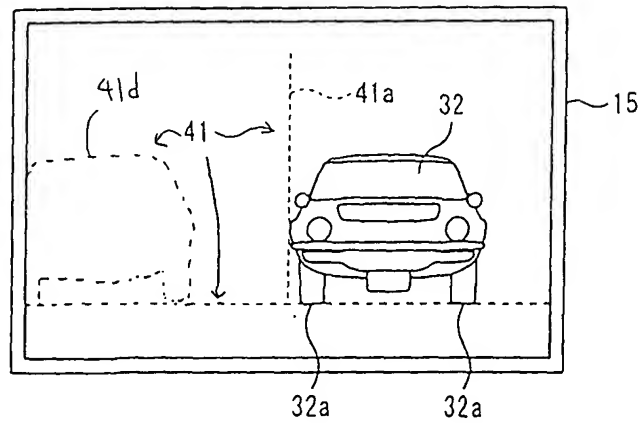


FIG. 7

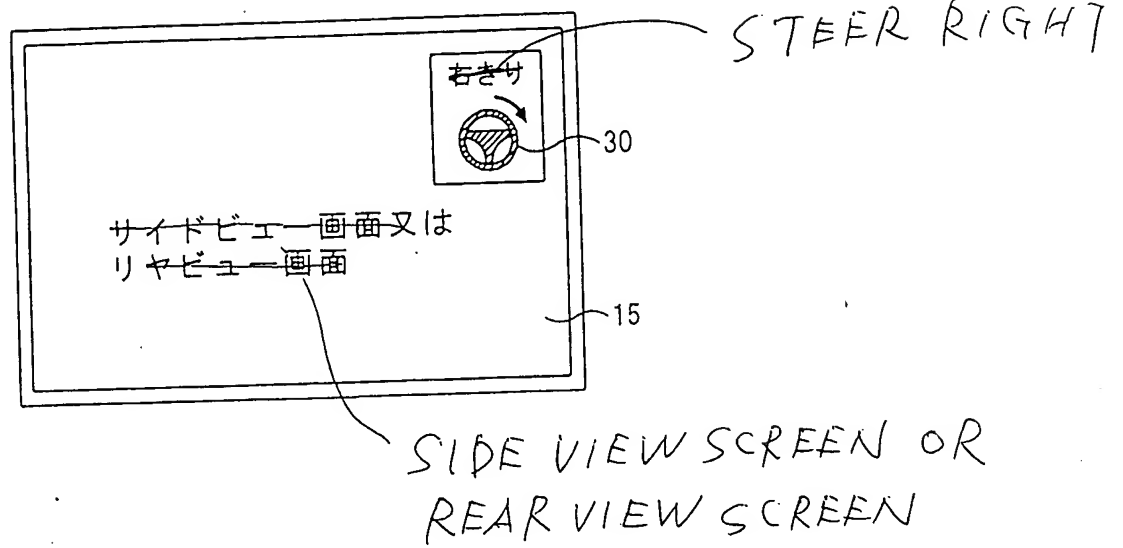


FIG. 8

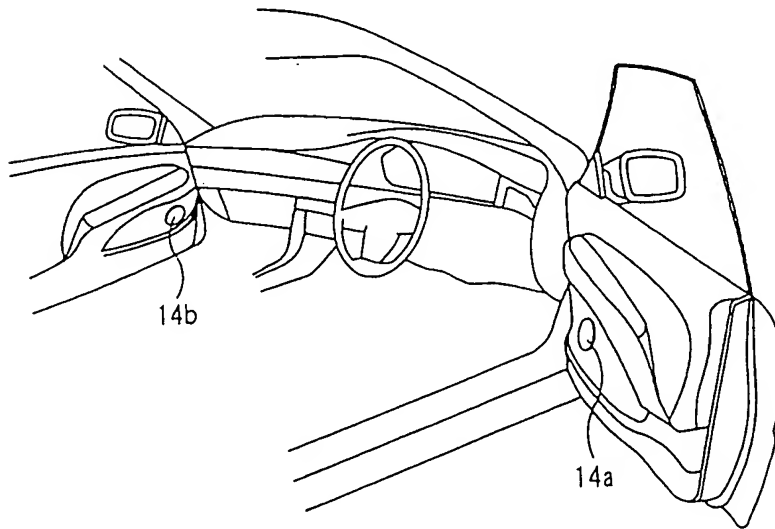


FIG. 9

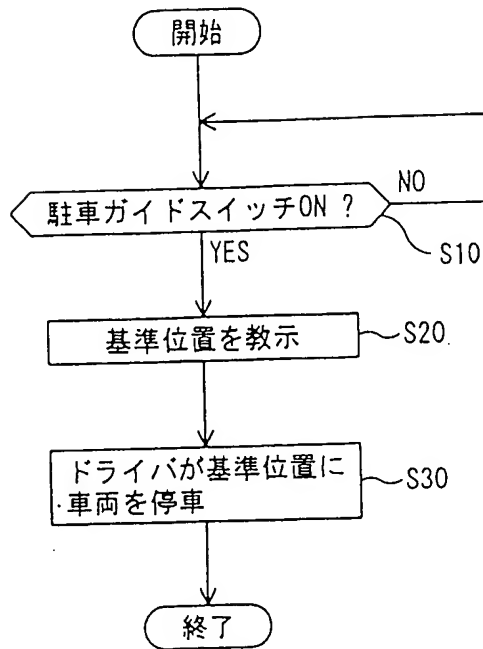


FIG. 10

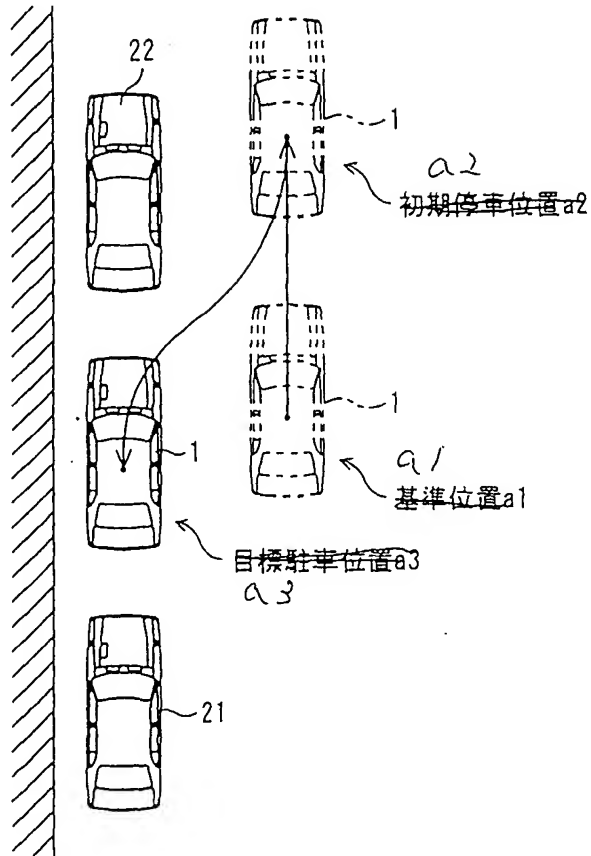


FIG. 11

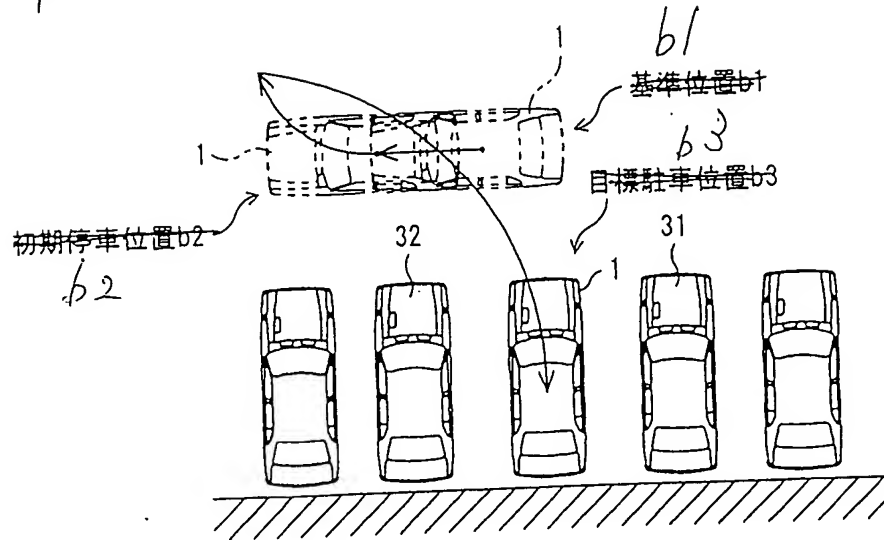


FIG. 12A

(a)

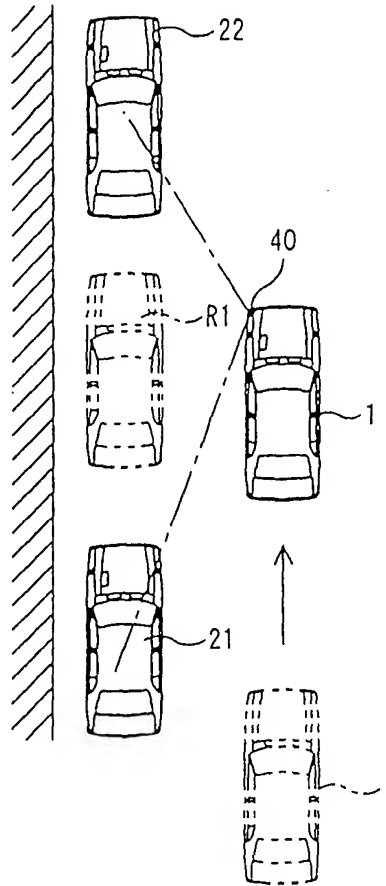


FIG. 12B

(b)

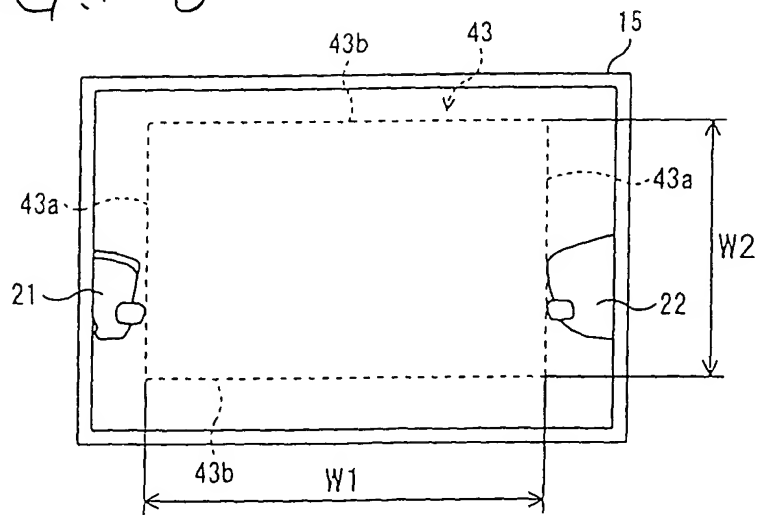


FIG. 12C

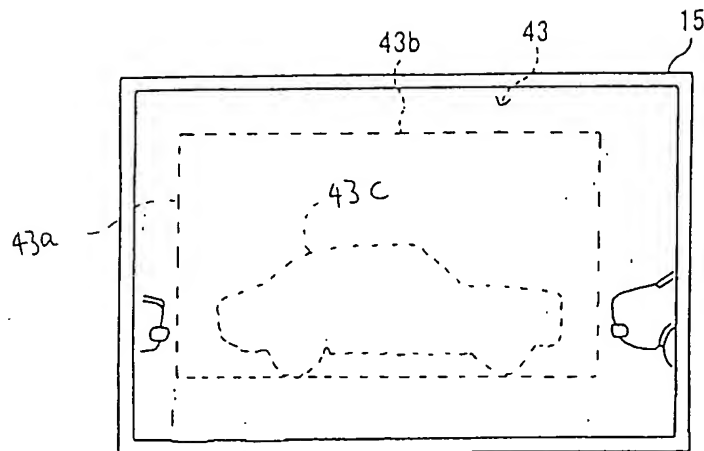


FIG. 13A

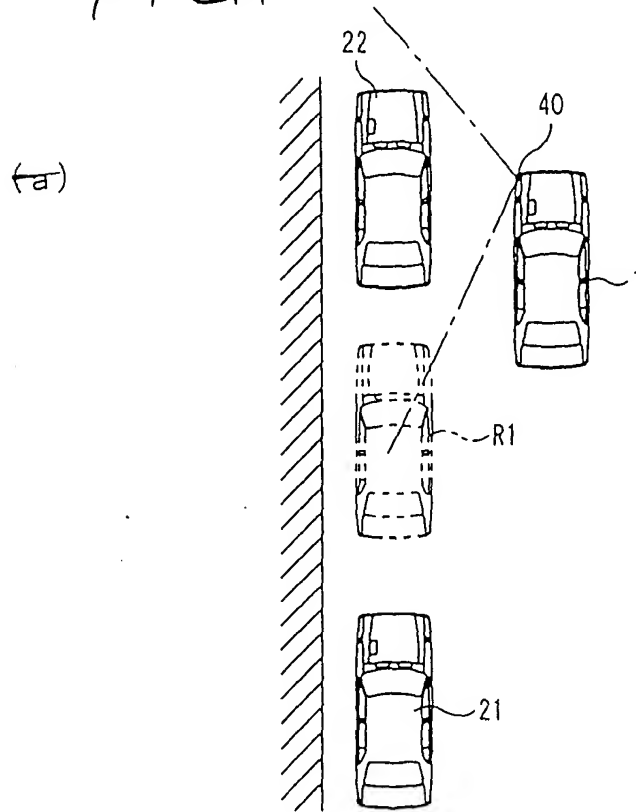


FIG. 13B

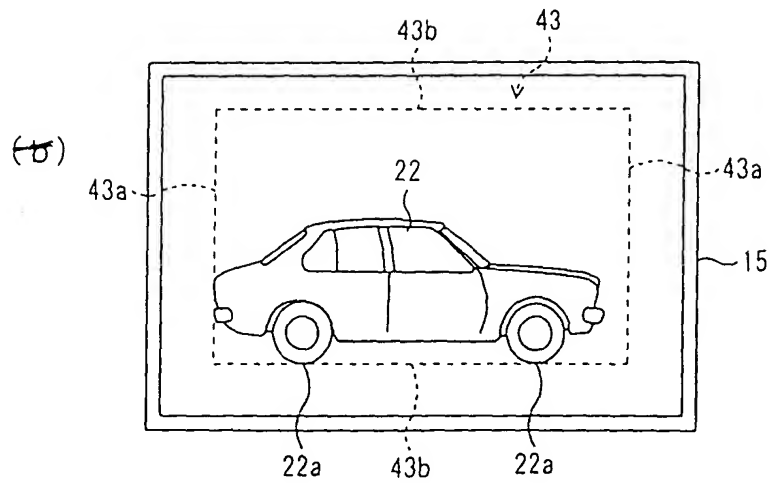
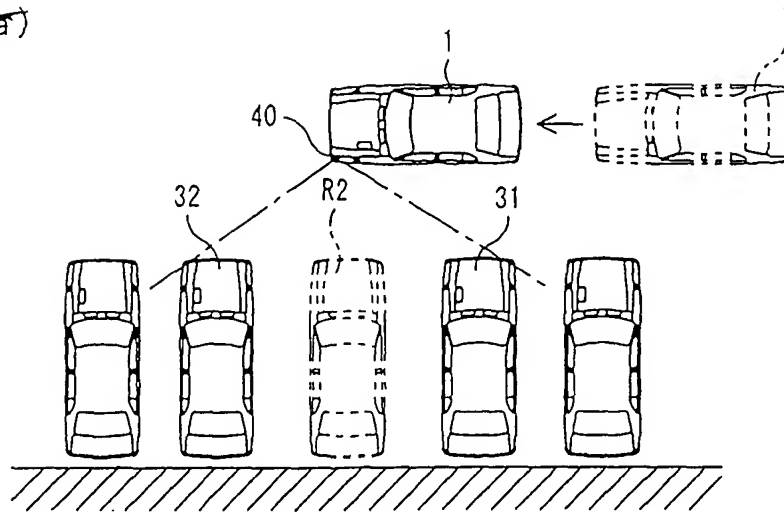


FIG. 14A

(a)



(b)

FIG. 14B

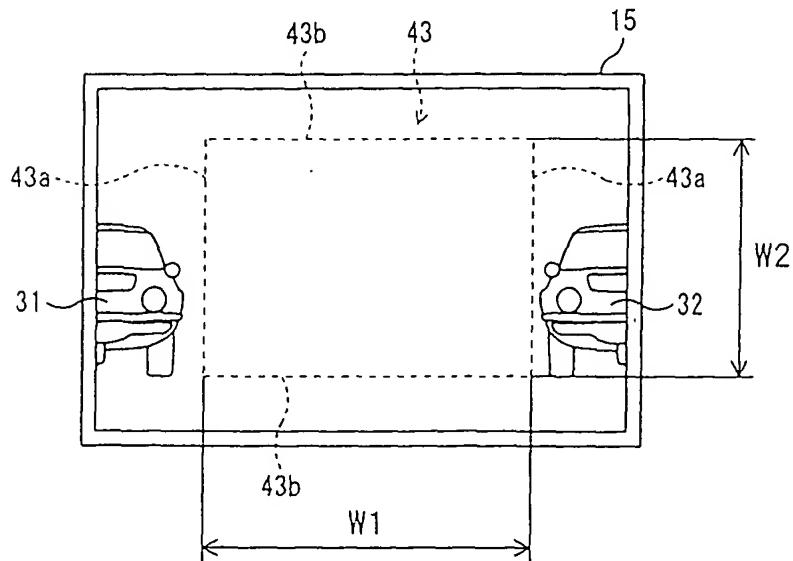
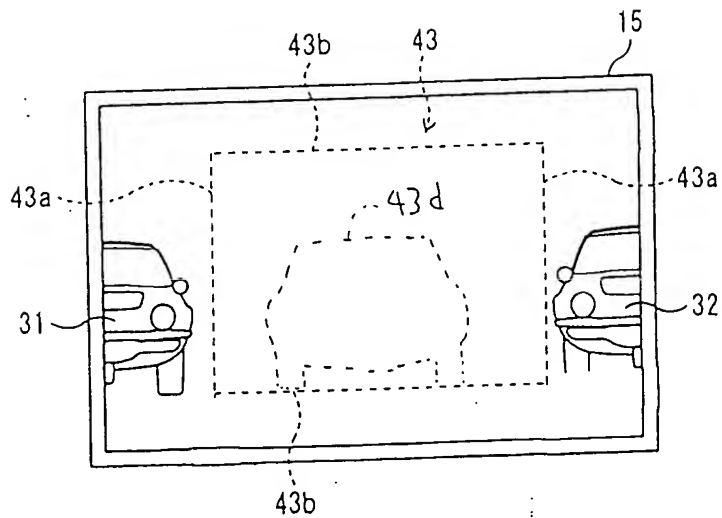
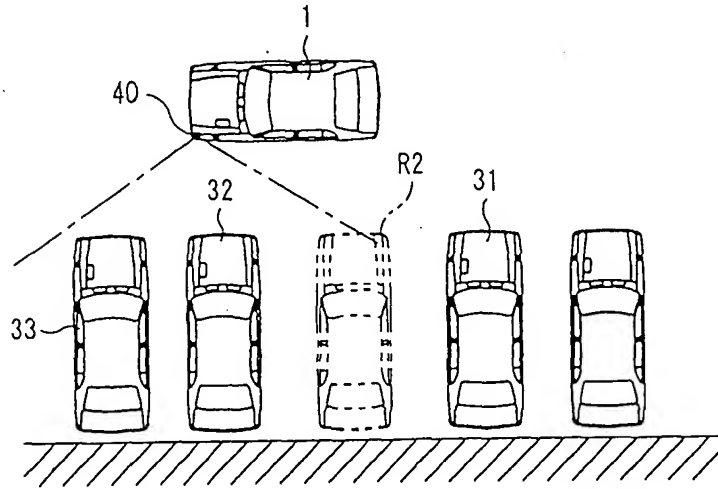


FIG. 14C



(a) FIG. 15A



(b) FIG. 15B

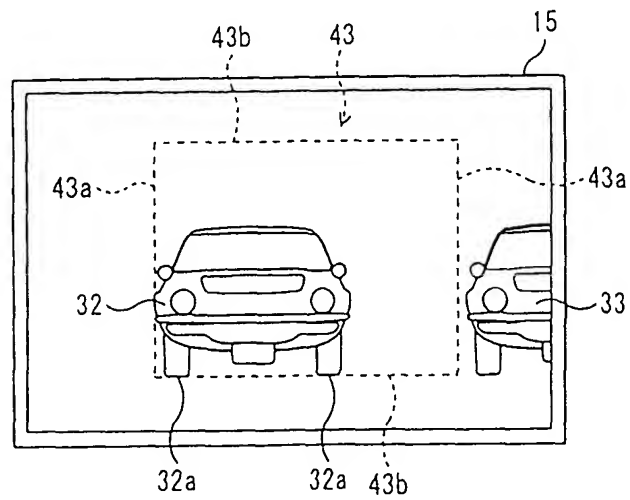


FIG. 16

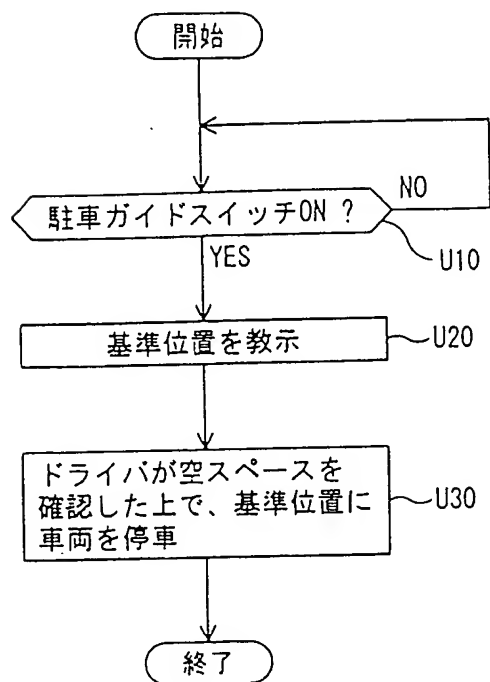


FIG. 17A

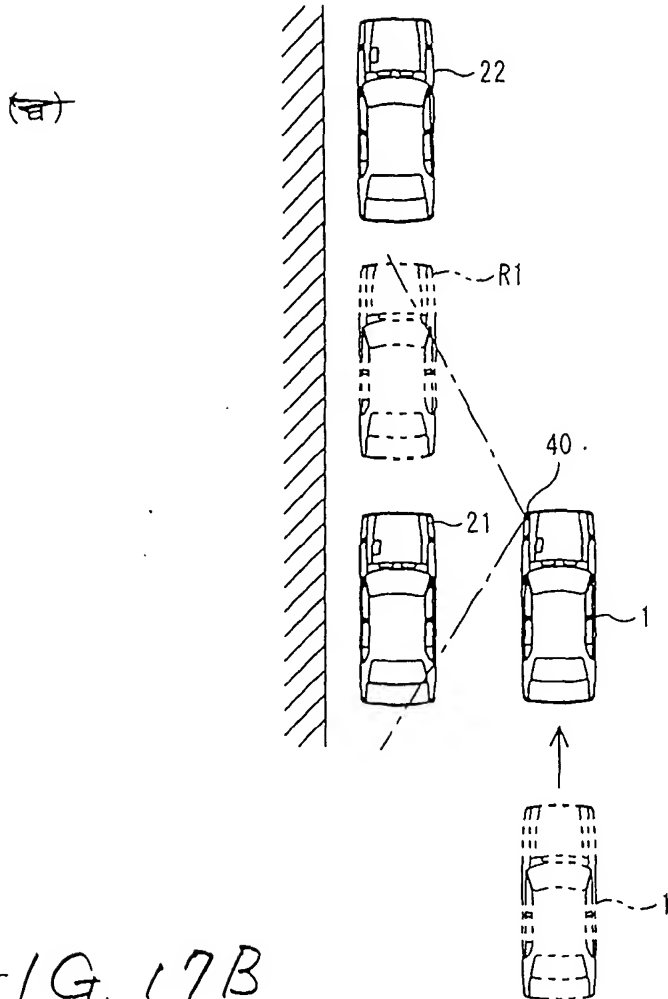


FIG. 17B

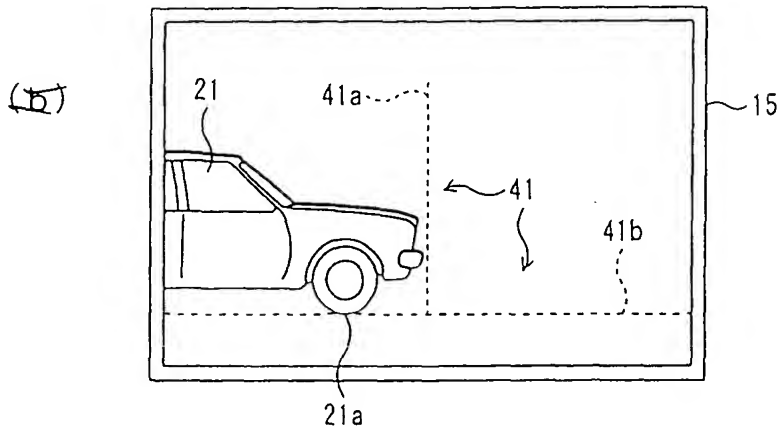


FIG. 17C

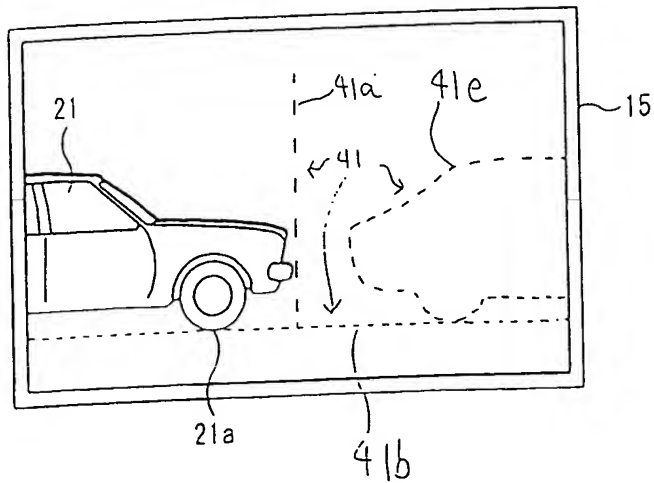


FIG. 18A

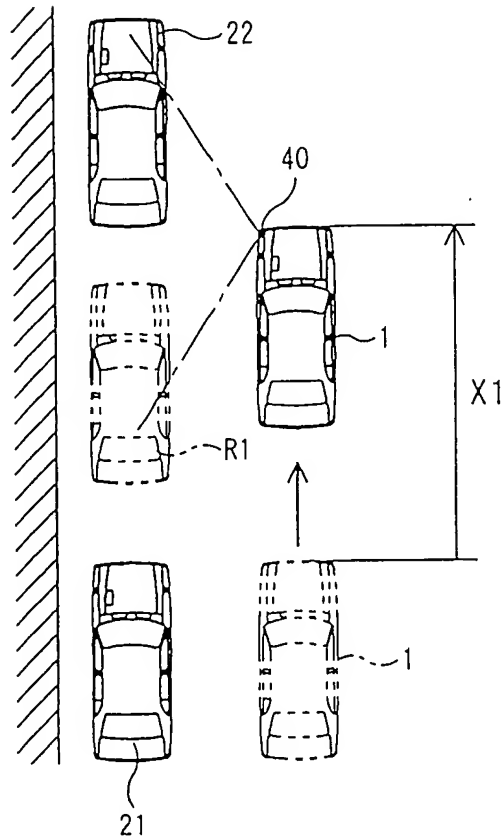


FIG. 18B

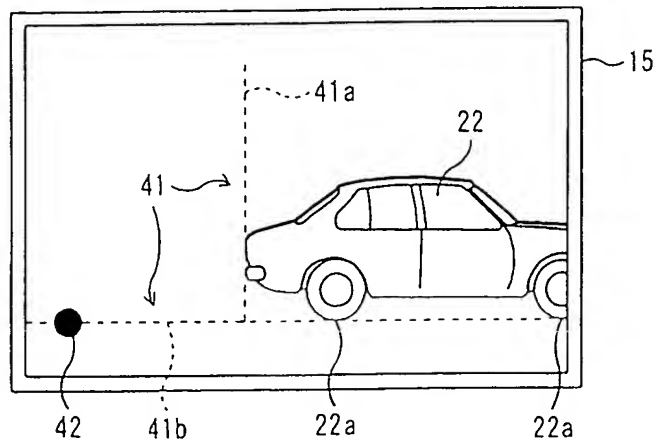


FIG. 18C

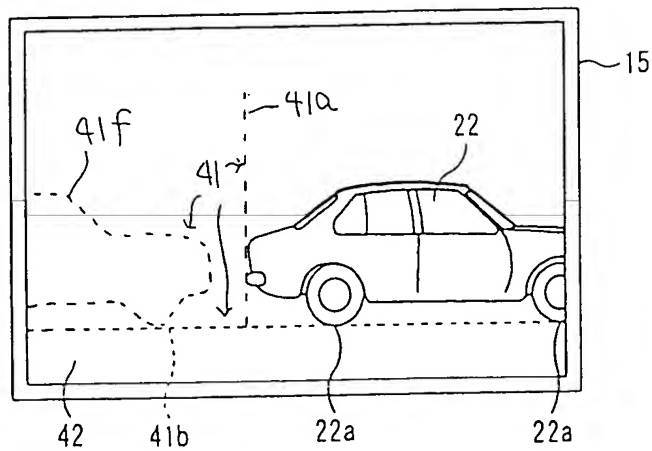


FIG. 19A

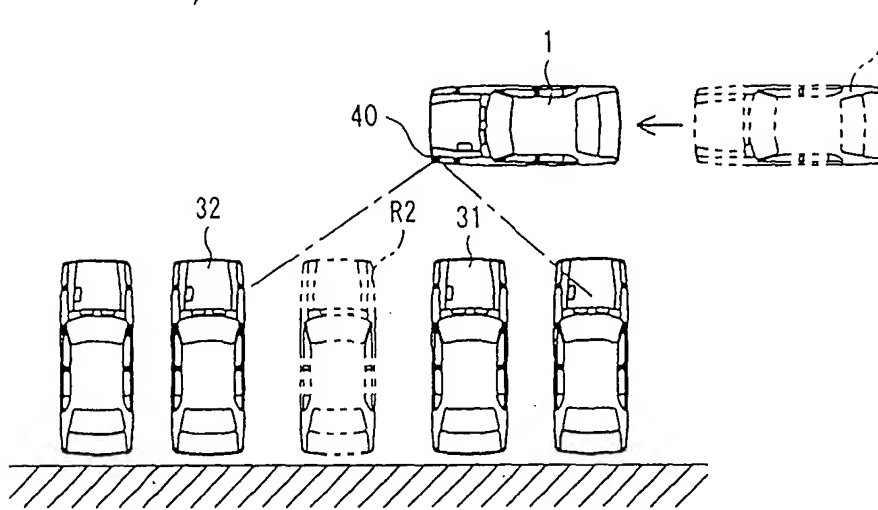


FIG. 19B

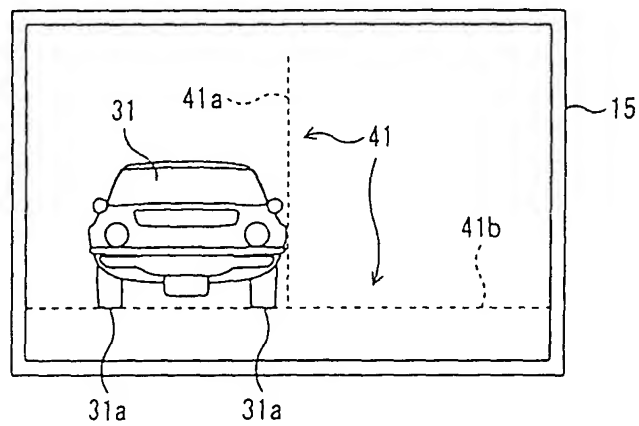


Diagram illustrating a vehicle 1 positioned above a row of vehicles 31, 32, and 33. A sensor 40 is located on the front of vehicle 1, and a range R2 is indicated by a dashed line extending from the sensor towards the vehicles below. A dimension X2 is shown as the horizontal distance from the front of vehicle 1 to the front of vehicle 31.

(b) FIG. 20B

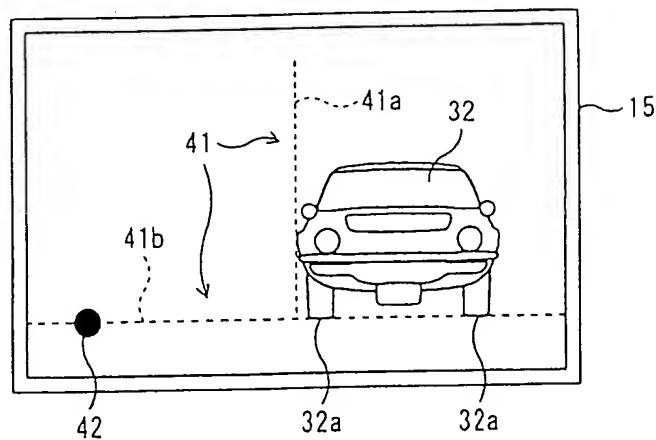


FIG. 21

